

NLS equation on metric graphs with localized nonlinearities

Lorenzo Tentarelli

Dipartimento di Scienze Matematiche "G.L. Lagrange" – Politecnico di Torino

joint work with Enrico Serra

TQMS – Como 09/07/2015

1 Introduction

2 Existence and nonexistence of ground states

3 Existence of multiple bound states

Some background

Applications:

- the study of the **NLS equation on graphs** arises in complex networks, quantum chaotic systems and Bose–Einstein condensates (**Gnutzmann, Smilansky - 2006**);
- the issue of **localized nonlinearity** is of interest in transmission through complex networks of one–dimensional leads, e.g. optical fiber (**Gnutzmann, Smilansky, Derevyanko - 2011**).

Mathematical background:

- NLS with localized nonlinearities in standard domains (different point of view): **Adami, Dell'Antonio, Figari, Teta – 2003; Cacciapuoti, Finco, Noja, Teta – 2014**;
- NLS with non-localized nonlinearities on graphs: **Adami, Cacciapuoti, Finco, Noja – 2012, 2014; Adami, Serra, Tilli – 2014, 2015**.

Some background

Applications:

- the study of the **NLS equation on graphs** arises in complex networks, quantum chaotic systems and Bose–Einstein condensates (**Gnutzmann, Smilansky - 2006**);
- the issue of **localized nonlinearity** is of interest in transmission through complex networks of one–dimensional leads, e.g. optical fiber (**Gnutzmann, Smilansky, Derevyanko - 2011**).

Mathematical background:

- NLS with localized nonlinearities in standard domains (different point of view): **Adami, Dell'Antonio, Figari, Teta – 2003; Cacciapuoti, Finco, Noja, Teta – 2014**;
- NLS with non-localized nonlinearities on graphs: **Adami, Cacciapuoti, Finco, Noja – 2012, 2014; Adami, Serra, Tilli – 2014, 2015**.

Some background

Applications:

- the study of the **NLS equation on graphs** arises in complex networks, quantum chaotic systems and Bose–Einstein condensates (**Gnutzmann, Smilansky - 2006**);
- the issue of **localized nonlinearity** is of interest in transmission through complex networks of one–dimensional leads, e.g. optical fiber (**Gnutzmann, Smilansky, Derevyanko - 2011**).

Mathematical background:

- NLS with localized nonlinearities in standard domains (different point of view): **Adami, Dell'Antonio, Figari, Teta – 2003; Cacciapuoti, Finco, Noja, Teta – 2014**;
- NLS with non-localized nonlinearities on graphs: **Adami, Cacciapuoti, Finco, Noja – 2012, 2014; Adami, Serra, Tilli – 2014, 2015**.

Some background

Applications:

- the study of the **NLS equation on graphs** arises in complex networks, quantum chaotic systems and Bose–Einstein condensates (**Gnutzmann, Smilansky - 2006**);
- the issue of **localized nonlinearity** is of interest in transmission through complex networks of one–dimensional leads, e.g. optical fiber (**Gnutzmann, Smilansky, Derevyanko - 2011**).

Mathematical background:

- NLS with localized nonlinearities in standard domains (different point of view): **Adami, Dell'Antonio, Figari, Teta – 2003; Cacciapuoti, Finco, Noja, Teta – 2014**;
- NLS with non-localized nonlinearities on graphs: **Adami, Cacciapuoti, Finco, Noja – 2012, 2014; Adami, Serra, Tilli – 2014, 2015**.

Basics on metric graphs

As usual, with (connected) **metric graph** we mean a **multigraph**

$$\mathcal{G} = (V, E)$$

(possibly **multiple edges** and **self-loops**), where each edge e joining two vertices v_1 and v_2 is associated either with a **closed bounded interval**

$$I_e = [0, \ell_e] \subset \mathbb{R} \quad \Rightarrow \quad e \text{ is a } \text{bounded edge}$$

or with a **half-line**

$$I_e = [0, +\infty) \subset \mathbb{R} \quad \Rightarrow \quad e \text{ is an } \text{unbounded edge.}$$

Basics on metric graphs

As usual, with (connected) **metric graph** we mean a **multigraph**

$$\mathcal{G} = (V, E)$$

(possibly **multiple edges** and **self-loops**), where each edge e joining two vertices v_1 and v_2 is associated either with a **closed bounded interval**

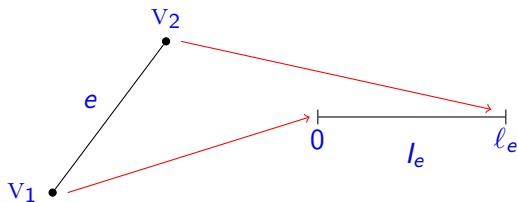
$$I_e = [0, \ell_e] \subset \mathbb{R} \quad \Rightarrow \quad e \text{ is a } \text{bounded edge}$$

or with a **half-line**

$$I_e = [0, +\infty) \subset \mathbb{R} \quad \Rightarrow \quad e \text{ is an } \text{unbounded edge}.$$

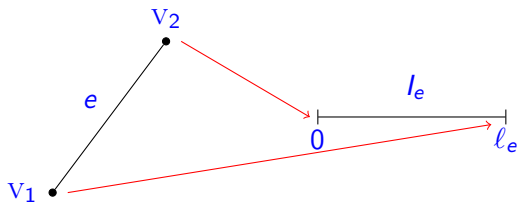
Basics on metric graphs

Moreover, a **coordinate** x_e is chosen in I_e , so that v_1 corresponds to $x_e = 0$ and v_2 to $x_e = l_e$



Basics on metric graphs

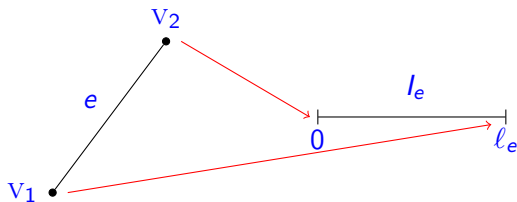
Moreover, a **coordinate** x_e is chosen in I_e , so that v_1 corresponds to $x_e = 0$ and v_2 to $x_e = \ell_e$ or **viceversa**.



If $\ell_e = +\infty$, we always assume that the **half-line** I_e is attached to the graph at $x_e = 0$, and the vertex corresponding to $x_e = +\infty$ is called a **vertex at infinity**.

Basics on metric graphs

Moreover, a **coordinate** x_e is chosen in I_e , so that v_1 corresponds to $x_e = 0$ and v_2 to $x_e = l_e$ or **viceversa**.



If $l_e = +\infty$, we always assume that the **half-line** I_e is attached to the graph at $x_e = 0$, and the vertex corresponding to $x_e = +\infty$ is called a **vertex at infinity**.

Compact core

We say that a metric graph \mathcal{G} is **compact** if it does **not** contain any **unbounded** edge (or, equivalently, any **vertex at infinity**).

Definition

The **compact core** \mathcal{K} is the metric subgraph of \mathcal{G} consisting of all the **bounded** edges (and the related vertices).

Note that:

- \mathcal{K} is a compact metric graph;
- \mathcal{K} can be **empty**;
- if \mathcal{G} is compact (and non-trivial), then $\mathcal{K} = \mathcal{G}$.

Compact core

We say that a metric graph \mathcal{G} is **compact** if it does **not** contain any **unbounded** edge (or, equivalently, any **vertex at infinity**).

Definition

The **compact core** \mathcal{K} is the metric subgraph of \mathcal{G} consisting of all the **bounded** edges (and the related vertices).

Note that:

- \mathcal{K} is a compact metric graph;
- \mathcal{K} can be **empty**;
- if \mathcal{G} is compact (and non-trivial), then $\mathcal{K} = \mathcal{G}$.

Compact core

We say that a metric graph \mathcal{G} is **compact** if it does **not** contain any **unbounded** edge (or, equivalently, any **vertex at infinity**).

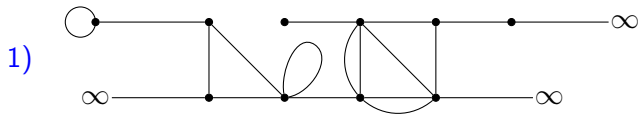
Definition

The **compact core** \mathcal{K} is the metric subgraph of \mathcal{G} consisting of all the **bounded** edges (and the related vertices).

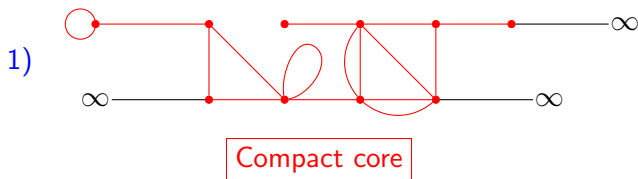
Note that:

- \mathcal{K} is a compact metric graph;
- \mathcal{K} can be **empty**;
- if \mathcal{G} is compact (and non-trivial), then $\mathcal{K} = \mathcal{G}$.

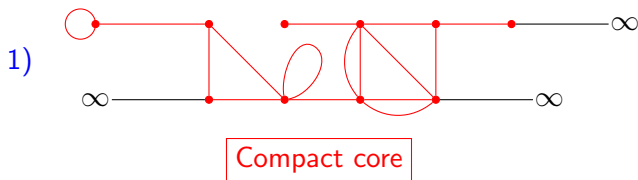
Examples



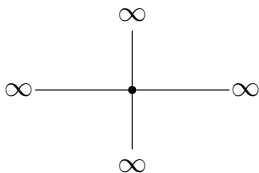
Examples



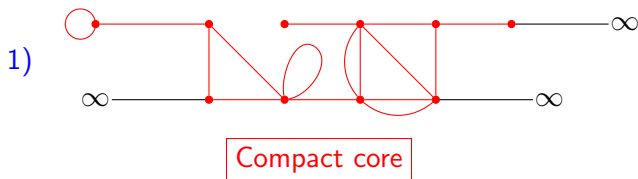
Examples



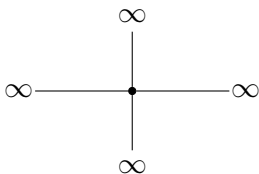
2)



Examples



2)



Compact core $\Rightarrow \emptyset$

Functions on graphs

A function $u : \mathcal{G} \rightarrow \mathbb{R}$ is a **family** of functions $u = (u_e)_{e \in \mathbb{E}}$, with

$$u_e : I_e \rightarrow \mathbb{R} \quad \forall e \in \mathbb{E}.$$

The usual **Lebesgue** function spaces can be defined as

$$u \in L^p(\mathcal{G}) \Leftrightarrow u_e \in L^p(I_e) \quad \forall e \in \mathbb{E}, \quad \|u\|_{L^p(\mathcal{G})}^p = \sum_{e \in \mathbb{E}} \|u_e\|_{L^p(I_e)}^p,$$

while $H^1(\mathcal{G})$ is the set of **continuous** $u = (u_e)_e$ s.t.

$$u_e \in H^1(I_e) \quad \forall e \in \mathbb{E}, \quad \|u\|_{H^1(\mathcal{G})}^2 = \sum_{e \in \mathbb{E}} \|u_e\|_{H^1(I_e)}^2.$$

Note: **Continuity=no jump at vertices.**

Functions on graphs

A function $u : \mathcal{G} \rightarrow \mathbb{R}$ is a **family** of functions $u = (u_e)_{e \in \mathbb{E}}$, with

$$u_e : I_e \rightarrow \mathbb{R} \quad \forall e \in \mathbb{E}.$$

The usual **Lebesgue** function spaces can be defined as

$$u \in L^p(\mathcal{G}) \Leftrightarrow u_e \in L^p(I_e) \quad \forall e \in \mathbb{E}, \quad \|u\|_{L^p(\mathcal{G})}^p = \sum_{e \in \mathbb{E}} \|u_e\|_{L^p(I_e)}^p,$$

while $H^1(\mathcal{G})$ is the set of **continuous** $u = (u_e)_e$ s.t.

$$u_e \in H^1(I_e) \quad \forall e \in \mathbb{E}, \quad \|u\|_{H^1(\mathcal{G})}^2 = \sum_{e \in \mathbb{E}} \|u_e\|_{H^1(I_e)}^2.$$

Note: **Continuity=no jump at vertices.**

Functions on graphs

A function $u : \mathcal{G} \rightarrow \mathbb{R}$ is a **family** of functions $u = (u_e)_{e \in \mathbb{E}}$, with

$$u_e : I_e \rightarrow \mathbb{R} \quad \forall e \in \mathbb{E}.$$

The usual **Lebesgue** function spaces can be defined as

$$u \in L^p(\mathcal{G}) \Leftrightarrow u_e \in L^p(I_e) \quad \forall e \in \mathbb{E}, \quad \|u\|_{L^p(\mathcal{G})}^p = \sum_{e \in \mathbb{E}} \|u_e\|_{L^p(I_e)}^p,$$

while $H^1(\mathcal{G})$ is the set of **continuous** $u = (u_e)_e$ s.t.

$$u_e \in H^1(I_e) \quad \forall e \in \mathbb{E}, \quad \|u\|_{H^1(\mathcal{G})}^2 = \sum_{e \in \mathbb{E}} \|u_e\|_{H^1(I_e)}^2.$$

Note: **Continuity**=no jump at vertices.

Bound states of prescribed mass

Let \mathcal{G} be a metric graph with **nonempty** \mathcal{K} and let $p \in [2, +\infty)$.

A **bound state of mass** $\mu > 0$ can be characterized as a function $u \in H^1(\mathcal{G})$, with $\|u\|_{L^2(\mathcal{G})}^2 = \mu$, for which:

(i) there exists $\lambda \in \mathbb{R}$ s.t.

$$u_e'' + \chi_{\mathcal{K}}(x)|u_e|^{p-2} u_e = \lambda u_e \quad (\text{stationary NLS equation});$$

(ii) for every vertex v in \mathcal{K}

$$\sum_{e \ni v} \frac{du_e}{dx_e}(v) = 0 \quad (\text{Kirchhoff condition}).$$

Note: $du_e/dx_e(v)$ stands for $u_e'(0)$ or $-u_e'(\ell_e)$ depending on the **orientation** of l_e .

Bound states of prescribed mass

Let \mathcal{G} be a metric graph with **nonempty** \mathcal{K} and let $p \in [2, +\infty)$.

A **bound state of mass** $\mu > 0$ can be characterized as a function $u \in H^1(\mathcal{G})$, with $\|u\|_{L^2(\mathcal{G})}^2 = \mu$, for which:

(i) there exists $\lambda \in \mathbb{R}$ s.t.

$$u_e'' + \chi_{\mathcal{K}}(x)|u_e|^{p-2} u_e = \lambda u_e \quad (\text{stationary NLS equation});$$

(ii) for every vertex v in \mathcal{K}

$$\sum_{e \succ v} \frac{du_e}{dx_e}(v) = 0 \quad (\text{Kirchhoff condition}).$$

Note: $du_e/dx_e(v)$ stands for $u_e'(0)$ or $-u_e'(\ell_e)$ depending on the **orientation** of l_e .

Bound states of prescribed mass

Let \mathcal{G} be a metric graph with **nonempty** \mathcal{K} and let $p \in [2, +\infty)$.

A **bound state of mass** $\mu > 0$ can be characterized as a function $u \in H^1(\mathcal{G})$, with $\|u\|_{L^2(\mathcal{G})}^2 = \mu$, for which:

(i) there exists $\lambda \in \mathbb{R}$ s.t.

$$u_e'' + \chi_{\mathcal{K}}(x)|u_e|^{p-2} u_e = \lambda u_e \quad (\text{stationary NLS equation});$$

(ii) for every vertex v in \mathcal{K}

$$\sum_{e \succ v} \frac{du_e}{dx_e}(v) = 0 \quad (\text{Kirchhoff condition}).$$

Note: $du_e/dx_e(v)$ stands for $u_e'(0)$ or $-u_e'(\ell_e)$ depending on the **orientation** of l_e .

Bound states of prescribed mass

Let \mathcal{G} be a metric graph with **nonempty** \mathcal{K} and let $p \in [2, +\infty)$.

A **bound state of mass** $\mu > 0$ can be characterized as a function $u \in H^1(\mathcal{G})$, with $\|u\|_{L^2(\mathcal{G})}^2 = \mu$, for which:

(i) there exists $\lambda \in \mathbb{R}$ s.t.

$$u_e'' + \chi_{\mathcal{K}}(x)|u_e|^{p-2} u_e = \lambda u_e \quad (\text{stationary NLS equation});$$

(ii) for every vertex v in \mathcal{K}

$$\sum_{e \succ v} \frac{du_e}{dx_e}(v) = 0 \quad (\text{Kirchhoff condition}).$$

Note: $du_e/dx_e(v)$ stands for $u_e'(0)$ or $-u_e'(\ell_e)$ depending on the **orientation** of l_e .

Connection with the NLS energy

Let $E : H^1(\mathcal{G}) \rightarrow \mathbb{R}$ be the **functional**

$$E(u) = \frac{1}{2} \|u'\|_{L^2(\mathcal{G})}^2 - \frac{1}{p} \|u\|_{L^p(\mathcal{K})}^p = \frac{1}{2} \int_{\mathcal{G}} |u'|^2 dx - \frac{1}{p} \int_{\mathcal{K}} |u|^p dx.$$

For fixed $\mu > 0$ define

$$M = \{u \in H^1(\mathcal{G}) : \|u\|_{L^2(\mathcal{G})}^2 = \mu\}$$

and denote by E_M the **restriction** of E to M . Then, E_M is of class C^1 and **critical points** of E_M satisfy

$$\int_{\mathcal{G}} u' \varphi' dx - \int_{\mathcal{K}} |u|^{p-2} u \varphi dx + \lambda \int_{\mathcal{G}} u \varphi dx = 0 \quad \forall \varphi \in H^1(\mathcal{G}),$$



Critical points of E_M = Bound states of mass μ .

Connection with the NLS energy

Let $E : H^1(\mathcal{G}) \rightarrow \mathbb{R}$ be the **functional**

$$E(u) = \frac{1}{2} \|u'\|_{L^2(\mathcal{G})}^2 - \frac{1}{p} \|u\|_{L^p(\mathcal{K})}^p = \frac{1}{2} \int_{\mathcal{G}} |u'|^2 dx - \frac{1}{p} \int_{\mathcal{K}} |u|^p dx.$$

For fixed $\mu > 0$ define

$$M = \{u \in H^1(\mathcal{G}) : \|u\|_{L^2(\mathcal{G})}^2 = \mu\}$$

and denote by E_M the **restriction** of E to M . Then, E_M is of class C^1 and **critical points** of E_M satisfy

$$\int_{\mathcal{G}} u' \varphi' dx - \int_{\mathcal{K}} |u|^{p-2} u \varphi dx + \lambda \int_{\mathcal{G}} u \varphi dx = 0 \quad \forall \varphi \in H^1(\mathcal{G}),$$



Critical points of E_M = Bound states of mass μ .

Connection with the NLS energy

Let $E : H^1(\mathcal{G}) \rightarrow \mathbb{R}$ be the **functional**

$$E(u) = \frac{1}{2} \|u'\|_{L^2(\mathcal{G})}^2 - \frac{1}{p} \|u\|_{L^p(\mathcal{K})}^p = \frac{1}{2} \int_{\mathcal{G}} |u'|^2 dx - \frac{1}{p} \int_{\mathcal{K}} |u|^p dx.$$

For fixed $\mu > 0$ define

$$M = \{u \in H^1(\mathcal{G}) : \|u\|_{L^2(\mathcal{G})}^2 = \mu\}$$

and denote by E_M the **restriction** of E to M . Then, E_M is of class C^1 and **critical points** of E_M satisfy

$$\int_{\mathcal{G}} u' \varphi' dx - \int_{\mathcal{K}} |u|^{p-2} u \varphi dx + \lambda \int_{\mathcal{G}} u \varphi dx = 0 \quad \forall \varphi \in H^1(\mathcal{G}),$$



Critical points of E_M = Bound states of mass μ .

Connection with the NLS energy

Let $E : H^1(\mathcal{G}) \rightarrow \mathbb{R}$ be the **functional**

$$E(u) = \frac{1}{2} \|u'\|_{L^2(\mathcal{G})}^2 - \frac{1}{p} \|u\|_{L^p(\mathcal{K})}^p = \frac{1}{2} \int_{\mathcal{G}} |u'|^2 dx - \frac{1}{p} \int_{\mathcal{K}} |u|^p dx.$$

For fixed $\mu > 0$ define

$$M = \{u \in H^1(\mathcal{G}) : \|u\|_{L^2(\mathcal{G})}^2 = \mu\}$$

and denote by E_M the **restriction** of E to M . Then, E_M is of class C^1 and **critical points** of E_M satisfy

$$\int_{\mathcal{G}} u' \varphi' dx - \int_{\mathcal{K}} |u|^{p-2} u \varphi dx + \lambda \int_{\mathcal{G}} u \varphi dx = 0 \quad \forall \varphi \in H^1(\mathcal{G}),$$



Critical points of E_M = Bound states of mass μ .

Ground states of prescribed mass

Finally, we say that $u \in M$ is a *ground state of mass $\mu > 0$* if

$$E_M(u) = \inf_{v \in M} E_M(v).$$

Remarks:

- u is a critical point of E_M and hence a bound state of mass μ (the one with the least energy level);
- if u is a ground state, also $|u|$ is such and, by a *regularity argument*, this entails that $u > 0$.

Ground states of prescribed mass

Finally, we say that $u \in M$ is a *ground state of mass $\mu > 0$* if

$$E_M(u) = \inf_{v \in M} E_M(v).$$

Remarks:

- u is a critical point of E_M and hence a bound state of mass μ (*the one with the least energy level*);
- if u is a ground state, also $|u|$ is such and, by a *regularity argument*, this entails that $u > 0$.

Ground states of prescribed mass

Finally, we say that $u \in M$ is a *ground state of mass $\mu > 0$* if

$$E_M(u) = \inf_{v \in M} E_M(v).$$

Remarks:

- u is a critical point of E_M and hence a bound state of mass μ (*the one with the least energy level*);
- if u is a ground state, also $|u|$ is such and, by a *regularity argument*, this entails that $u > 0$.

1 Introduction

2 Existence and nonexistence of ground states

3 Existence of multiple bound states

A general result

Theorem – T. – 2015

Let \mathcal{G} be a **noncompact** connected metric graph with **nonempty** compact core \mathcal{K} . Let $p \in (2, 6)$ and $\mu > 0$. Then

$$\inf_{v \in M} E_M(v) \leq 0.$$

Moreover, if $\inf_{v \in M} E_M(v) < 0$, then the infimum is **attained**.

Note: the case $p \in (2, 6)$ is usually called L^2 -**subcritical case**.

Note: in the sequel we **tacitly** suppose that \mathcal{G} , \mathcal{K} , p and μ always satisfy the previous assumptions.

A general result

Theorem – T. – 2015

Let \mathcal{G} be a **noncompact** connected metric graph with **nonempty** compact core \mathcal{K} . Let $p \in (2, 6)$ and $\mu > 0$. Then

$$\inf_{v \in M} E_M(v) \leq 0.$$

Moreover, if $\inf_{v \in M} E_M(v) < 0$, then the infimum is **attained**.

Note: the case $p \in (2, 6)$ is usually called **L^2 -subcritical case**.

Note: in the sequel we **tacitly** suppose that \mathcal{G} , \mathcal{K} , p and μ always satisfy the previous assumptions.

A general result

Theorem – T. – 2015

Let \mathcal{G} be a **noncompact** connected metric graph with **nonempty** compact core \mathcal{K} . Let $p \in (2, 6)$ and $\mu > 0$. Then

$$\inf_{v \in M} E_M(v) \leq 0.$$

Moreover, if $\inf_{v \in M} E_M(v) < 0$, then the infimum is **attained**.

Note: the case $p \in (2, 6)$ is usually called **L^2 -subcritical case**.

Note: in the sequel we **tacitly** suppose that \mathcal{G} , \mathcal{K} , p and μ always satisfy the previous assumptions.

Existence result

Theorem – T. – 2015

- If $p \in (2, 4)$, for every $\mu > 0$ there exists a **ground state of mass μ** .
- If $p \in [4, 6)$, there exists $\mu_1 > 0$ s.t., for every $\mu > \mu_1$, there exists a **ground state of mass μ** .

Note: μ_1 (not sharp in general) satisfies

$$\mu_1^{\frac{p-2}{6-p}} L = c_p N^{\frac{4}{6-p}}$$

where $L = \text{meas}(\mathcal{K})$, N is the number of **unbounded edges** of \mathcal{G} and c_p is a positive constant.

Existence result

Theorem – T. – 2015

- If $p \in (2, 4)$, for every $\mu > 0$ there exists a **ground state of mass μ** .
- If $p \in [4, 6)$, there exists $\mu_1 > 0$ s.t., for every $\mu > \mu_1$, there exists a **ground state of mass μ** .

Note: μ_1 (**not sharp** in general) satisfies

$$\mu_1^{\frac{p-2}{6-p}} L = c_p N^{\frac{4}{6-p}}$$

where $L = \text{meas}(\mathcal{K})$, N is the number of **unbounded edges** of \mathcal{G} and c_p is a positive constant.

Sketch of the proof

For $\alpha \in (0, \sqrt{\mu/L})$ and $m = \frac{\mu - \alpha^2 L}{N}$, define the **competitor**

$$u(x) = \begin{cases} \alpha & \text{in } \mathcal{K} \\ \alpha e^{-\frac{\alpha^2 x}{2m}} & \text{in each half-line.} \end{cases}$$

Then $E_M(u)$ reads

$$E_M(u) = \frac{\alpha^4 N^2}{8(\mu - \alpha^2 L)} - \frac{\alpha^p L}{p}$$

If $p \in (2, 4)$, then $E_M(u) < 0$ provided α is **small**. If $p \in [4, 6)$, then a **sufficient condition** to have a value $\alpha_0 \in (0, \sqrt{\mu/L})$ s.t. $E_M(u) < 0$ is that $\mu > \mu_1$.

Sketch of the proof

For $\alpha \in (0, \sqrt{\mu/L})$ and $m = \frac{\mu - \alpha^2 L}{N}$, define the **competitor**

$$u(x) = \begin{cases} \alpha & \text{in } \mathcal{K} \\ \alpha e^{-\frac{\alpha^2 x}{2m}} & \text{in each half-line.} \end{cases}$$

Then $E_M(u)$ reads

$$E_M(u) = \frac{\alpha^4 N^2}{8(\mu - \alpha^2 L)} - \frac{\alpha^p L}{p}$$

If $p \in (2, 4)$, then $E_M(u) < 0$ provided α is **small**. If $p \in [4, 6)$, then a **sufficient condition** to have a value $\alpha_0 \in (0, \sqrt{\mu/L})$ s.t. $E_M(u) < 0$ is that $\mu > \mu_1$.

Sketch of the proof

For $\alpha \in (0, \sqrt{\mu/L})$ and $m = \frac{\mu - \alpha^2 L}{N}$, define the **competitor**

$$u(x) = \begin{cases} \alpha & \text{in } \mathcal{K} \\ \alpha e^{-\frac{\alpha^2 x}{2m}} & \text{in each half-line.} \end{cases}$$

Then $E_M(u)$ reads

$$E_M(u) = \frac{\alpha^4 N^2}{8(\mu - \alpha^2 L)} - \frac{\alpha^p L}{p}$$

If $p \in (2, 4)$, then $E_M(u) < 0$ provided α is **small**. If $p \in [4, 6)$, then a **sufficient condition** to have a value $\alpha_0 \in (0, \sqrt{\mu/L})$ s.t. $E_M(u) < 0$ is that $\mu > \mu_1$.

Sketch of the proof

For $\alpha \in (0, \sqrt{\mu/L})$ and $m = \frac{\mu - \alpha^2 L}{N}$, define the **competitor**

$$u(x) = \begin{cases} \alpha & \text{in } \mathcal{K} \\ \alpha e^{-\frac{\alpha^2 x}{2m}} & \text{in each half-line.} \end{cases}$$

Then $E_M(u)$ reads

$$E_M(u) = \frac{\alpha^4 N^2}{8(\mu - \alpha^2 L)} - \frac{\alpha^p L}{p}$$

If $p \in (2, 4)$, then $E_M(u) < 0$ provided α is **small**. If $p \in [4, 6)$, then a **sufficient condition** to have a value $\alpha_0 \in (0, \sqrt{\mu/L})$ s.t. $E_M(u) < 0$ is that $\mu > \mu_1$.

Nonexistence result

The **threshold** on μ in the existence result is an actual phenomenon or a lack of our proof?

Nonexistence result

The **threshold** on μ in the existence result is an **actual phenomenon** ~~or a lack of our proof.~~

Theorem – T. – 2015

If $p \in [4, 6)$, there exists $\mu_2 > 0$ s.t., for every $\mu < \mu_2$, there **cannot** exist any **ground state of mass μ** .

Note: also μ_2 can be explicitly computed and satisfies

$$\mu_2^{\frac{p-2}{6-p}} L = C_p^{\frac{4-p}{6-p}} C_\infty^{-p},$$

where C_p and C_∞ are the constants of the L^p -version and the L^∞ -version (respectively) of the **Gagliardo-Nirenberg Inequality**.

Nonexistence result

The **threshold** on μ in the existence result is an **actual phenomenon** ~~or a lack of our proof.~~

Theorem – T. – 2015

If $p \in [4, 6)$, there exists $\mu_2 > 0$ s.t., for every $\mu < \mu_2$, there **cannot** exist any **ground state of mass μ** .

Note: also μ_2 can be explicitly computed and satisfies

$$\mu_2^{\frac{p-2}{6-p}} L = C_p^{\frac{4-p}{6-p}} C_\infty^{-p},$$

where C_p and C_∞ are the constants of the **L^p -version** and the **L^∞ -version** (respectively) of the **Gagliardo-Nirenberg Inequality**.

Partition of a graph

The number of unbounded edges N affects **existence** since

$$\mu_1 = (c_p L^{-1} N^{\frac{4}{6-p}})^{\frac{6-p}{p-2}}.$$

How is it that it does not affect **nonexistence** (recall that μ_2 does not depend on N)? \Rightarrow **Actually it does!**

Indeed, if $N \geq 2$, then we can **cover** \mathcal{G} with a family of metric graphs $(\mathcal{G}_i)_{i=1}^N$ ($2 \leq i \leq N$) **pairwise disjoint** (up to sets of zero measure) and such that each \mathcal{G}_i contains **at least an unbounded edge**. We call such a family a **partition** of \mathcal{G} .

Note: the partition of a metric graph is **not unique** in general.

Partition of a graph

The number of unbounded edges N affects **existence** since

$$\mu_1 = (c_p L^{-1} N^{\frac{4}{6-p}})^{\frac{6-p}{p-2}}.$$

How is it that it does not affect **nonexistence** (recall that μ_2 does not depend on N)? \Rightarrow **Actually it does!**

Indeed, if $N \geq 2$, then we can **cover** \mathcal{G} with a family of metric graphs $(\mathcal{G}_i)_{i=1}^N$ ($2 \leq i \leq N$) **pairwise disjoint** (up to sets of zero measure) and such that each \mathcal{G}_i contains **at least an unbounded edge**. We call such a family a **partition** of \mathcal{G} .

Note: the partition of a metric graph is **not unique** in general.

Partition of a graph

The number of unbounded edges N affects **existence** since

$$\mu_1 = (c_p L^{-1} N^{\frac{4}{6-p}})^{\frac{6-p}{p-2}}.$$

How is it that it does not affect **nonexistence** (recall that μ_2 does not depend on N)? \Rightarrow **Actually it does!**

Indeed, if $N \geq 2$, then we can **cover** \mathcal{G} with a family of metric graphs $(\mathcal{G}_i)_{i=1}^N$ ($2 \leq i \leq N$) **pairwise disjoint** (up to sets of zero measure) and such that each \mathcal{G}_i contains **at least an unbounded edge**. We call such a family a **partition** of \mathcal{G} .

Note: the partition of a metric graph is **not unique** in general.

Partition of a graph

The number of unbounded edges N affects **existence** since

$$\mu_1 = (c_p L^{-1} N^{\frac{4}{6-p}})^{\frac{6-p}{p-2}}.$$

How is it that it does not affect **nonexistence** (recall that μ_2 does not depend on N)? \Rightarrow **Actually it does!**

Indeed, if $N \geq 2$, then we can **cover** \mathcal{G} with a family of metric graphs $(\mathcal{G}_i)_{i=1}^N$ ($2 \leq \nu \leq N$) **pairwise disjoint** (up to sets of zero measure) and such that each \mathcal{G}_i contains **at least an unbounded edge**. We call such a family a **partition** of \mathcal{G} .

Note: the partition of a metric graph is **not unique** in general.

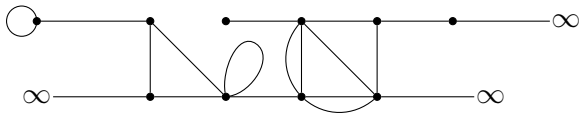
Example

Consider the graph \mathcal{G} of the beginning ($N = 3$).



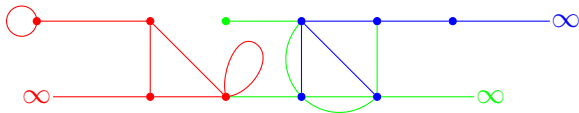
Example

Consider the graph \mathcal{G} of the beginning ($N = 3$).



Example

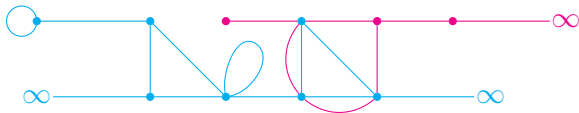
Consider the graph \mathcal{G} of the beginning ($N = 3$).



A possible partition is given by \mathcal{G}_1 , \mathcal{G}_2 , \mathcal{G}_3 .

Example

Consider the graph \mathcal{G} of the beginning ($N = 3$).



A possible partition is given by $\mathcal{G}_1, \mathcal{G}_2, \mathcal{G}_3$.

Another one by $\mathcal{G}_4, \mathcal{G}_5$.

And so on ...

Improvement of nonexistence

Corollary – T. – 2015

Let $(\mathcal{G}_i)_{i=1}^\nu$ be a **partition** of \mathcal{G} . Setting $L_i = \text{meas}(\mathcal{G}_i \cap \mathcal{K})$, if

$$\mu^{\frac{p-2}{6-p}} < \widehat{\mu}_i^{\frac{p-2}{6-p}} = L_i^{-1} C_p^{\frac{4-p}{6-p}} C_\infty^{-p} \quad \forall i \in \{1, \dots, \nu\},$$

then E_M **does not** admit a **minimizer**.

How can this corollary “**improve**” the previous result? Example:
double bridge graph.



Improvement of nonexistence

Corollary – T. – 2015

Let $(\mathcal{G}_i)_{i=1}^{\nu}$ be a **partition** of \mathcal{G} . Setting $L_i = \text{meas}(\mathcal{G}_i \cap \mathcal{K})$, if

$$\mu^{\frac{p-2}{6-p}} < \hat{\mu}_i^{\frac{p-2}{6-p}} = L_i^{-1} C_p^{\frac{4-p}{6-p}} C_\infty^{-p} \quad \forall i \in \{1, \dots, \nu\},$$

then E_M **does not** admit a **minimizer**.

How can this corollary “**improve**” the previous result? Example:
double bridge graph.



Improvement of nonexistence

Corollary – T. – 2015

Let $(\mathcal{G}_i)_{i=1}^{\nu}$ be a **partition** of \mathcal{G} . Setting $L_i = \text{meas}(\mathcal{G}_i \cap \mathcal{K})$, if

$$\mu^{\frac{p-2}{6-p}} < \widehat{\mu}_i^{\frac{p-2}{6-p}} = L_i^{-1} C_p^{\frac{4-p}{6-p}} C_{\infty}^{-p} \quad \forall i \in \{1, \dots, \nu\},$$

then E_M **does not** admit a **minimizer**.

How can this corollary “**improve**” the previous result? Example:
double bridge graph.



Improvement of nonexistence

Corollary – T. – 2015

Let $(\mathcal{G}_i)_{i=1}^\nu$ be a **partition** of \mathcal{G} . Setting $L_i = \text{meas}(\mathcal{G}_i \cap \mathcal{K})$, if

$$\mu^{\frac{p-2}{6-p}} < \hat{\mu}_i^{\frac{p-2}{6-p}} = L_i^{-1} C_p^{\frac{4-p}{6-p}} C_\infty^{-p} \quad \forall i \in \{1, \dots, \nu\},$$

then E_M **does not** admit a **minimizer**.

How can this corollary “**improve**” the previous result? Example:
double bridge graph.



If one choose partition $\mathcal{G}_1, \mathcal{G}_2$, then $L_1 = L_2 = L/2$ and $\hat{\mu}_i > \mu_2$.

1 Introduction

2 Existence and nonexistence of ground states

3 Existence of multiple bound states

Basics on solitons

The **soliton of mass μ** is the **unique minimizer** (up to a change of sign and translations) of

$$\mathcal{E}(u) = \frac{1}{2} \int_{\mathbb{R}} |u'|^2 dx - \frac{1}{p} \int_{\mathbb{R}} |u|^p dx$$

and the **unique solution** of

$$u'' + |u|^{p-2} u = \lambda u$$

among functions $u \in H^1(\mathbb{R})$ satisfying $\|u\|_{L^2(\mathbb{R})}^2 = \mu$. In addition, this function is known **explicitly**

$$\varphi_{\mu}(x) = \mu^{\frac{2}{6-p}} \varphi_1 \left(\mu^{\frac{p-2}{6-p}} x \right)$$

with $\varphi_1(x) = C_p \operatorname{sech}^{\frac{2}{p-2}}(c_p x)$ and $C_p, c_p > 0$.

Basics on solitons

The **soliton of mass μ** is the **unique minimizer** (up to a change of sign and translations) of

$$\mathcal{E}(u) = \frac{1}{2} \int_{\mathbb{R}} |u'|^2 dx - \frac{1}{p} \int_{\mathbb{R}} |u|^p dx$$

and the **unique solution** of

$$u'' + |u|^{p-2} u = \lambda u$$

among functions $u \in H^1(\mathbb{R})$ satisfying $\|u\|_{L^2(\mathbb{R})}^2 = \mu$. In addition, this function is known **explicitly**

$$\varphi_{\mu}(x) = \mu^{\frac{2}{6-p}} \varphi_1 \left(\mu^{\frac{p-2}{6-p}} x \right)$$

with $\varphi_1(x) = C_p \operatorname{sech}^{\frac{2}{p-2}}(c_p x)$ and $C_p, c_p > 0$.

Basics on solitons

The **soliton of mass μ** is the **unique minimizer** (up to a change of sign and translations) of

$$\mathcal{E}(u) = \frac{1}{2} \int_{\mathbb{R}} |u'|^2 dx - \frac{1}{p} \int_{\mathbb{R}} |u|^p dx$$

and the **unique solution** of

$$u'' + |u|^{p-2} u = \lambda u$$

among functions $u \in H^1(\mathbb{R})$ satisfying $\|u\|_{L^2(\mathbb{R})}^2 = \mu$. In addition, this function is known **explicitly**

$$\varphi_{\mu}(x) = \mu^{\frac{2}{6-p}} \varphi_1 \left(\mu^{\frac{p-2}{6-p}} x \right)$$

with $\varphi_1(x) = C_p \operatorname{sech}^{\frac{2}{p-2}}(c_p x)$ and $C_p, c_p > 0$.

Existence of multiple bound states

Theorem – Serra, T. – 2015

For every $k \in \mathbb{N}$, there exists $\mu_k > 0$ such that for all $\mu \geq \mu_k$ there exist **at least** k distinct pairs $(\pm u_j)$ of **bound states of mass** μ .
Moreover, for every $j = 1, \dots, k$

$$E_M(\pm u_j) \leq j\mathcal{E}(\varphi_{\mu/j}) + \sigma_k(\mu) < 0$$

where $\sigma_k(\mu) \rightarrow 0$ (**exponentially fast**) as $\mu \rightarrow \infty$. Finally, for each j , the **Lagrange multiplier** λ_j related to u_j is **positive**.

Note: the result holds also if the **nonlinearity** is placed just on a nontrivial subgraph of \mathcal{K} (**even on a single edge**).

Existence of multiple bound states

Theorem – Serra, T. – 2015

For every $k \in \mathbb{N}$, there exists $\mu_k > 0$ such that for all $\mu \geq \mu_k$ there exist **at least** k distinct pairs $(\pm u_j)$ of **bound states of mass** μ .
Moreover, for every $j = 1, \dots, k$

$$E_M(\pm u_j) \leq j\mathcal{E}(\varphi_{\mu/j}) + \sigma_k(\mu) < 0$$

where $\sigma_k(\mu) \rightarrow 0$ (**exponentially fast**) as $\mu \rightarrow \infty$. Finally, for each j , the **Lagrange multiplier** λ_j related to u_j is **positive**.

Note: the result holds also if the **nonlinearity** is placed just on a nontrivial subgraph of \mathcal{K} (**even on a single edge**).

An “intermediate” phenomenon

Take, for instance \mathcal{G}



- In the **degenerate** case when the interval shrinks to a point ($\mathcal{K} = \emptyset$) the problem becomes **linear** \Rightarrow there **cannot exist any** bound state of mass μ .
- In the **degenerate** case when the interval extends to the whole real line ($\mathcal{K} = \mathcal{G}$) \Rightarrow there are **infinitely many** ground states of mass μ (the **solitons**), but **no** bound state at higher levels.

Nonlinearity on a “compact portion of positive measure” generates bound states at higher energies!

An “intermediate” phenomenon

Take, for instance \mathcal{G}



- In the **degenerate** case when the interval shrinks to a point ($\mathcal{K} = \emptyset$) the problem becomes **linear** \Rightarrow there **cannot exist any** bound state of mass μ .
- In the **degenerate** case when the interval extends to the whole real line ($\mathcal{K} = \mathcal{G}$) \Rightarrow there are **infinitely many** ground states of mass μ (the **solitons**), but **no** bound state at higher levels.

Nonlinearity on a “compact portion of positive measure” generates bound states at higher energies!

An “intermediate” phenomenon

Take, for instance \mathcal{G}



- In the **degenerate** case when the interval shrinks to a point ($\mathcal{K} = \emptyset$) the problem becomes **linear** \Rightarrow there **cannot exist any** bound state of mass μ .
- In the **degenerate** case when the interval extends to the whole real line ($\mathcal{K} = \mathcal{G}$) \Rightarrow there are **infinitely many** ground states of mass μ (the **solitons**), but **no** bound state at higher levels.

Nonlinearity on a “compact portion of positive measure” generates bound states at higher energies!

An “intermediate” phenomenon

Take, for instance \mathcal{G}



- In the **degenerate** case when the interval shrinks to a point ($\mathcal{K} = \emptyset$) the problem becomes **linear** \Rightarrow there **cannot exist any** bound state of mass μ .
- In the **degenerate** case when the interval extends to the whole real line ($\mathcal{K} = \mathcal{G}$) \Rightarrow there are **infinitely many** ground states of mass μ (the **solitons**), but **no** bound state **at higher levels**.

Nonlinearity on a “compact portion of positive measure” generates bound states at higher energies!

An “intermediate” phenomenon

Take, for instance \mathcal{G}



- In the **degenerate** case when the interval shrinks to a point ($\mathcal{K} = \emptyset$) the problem becomes **linear** \Rightarrow there **cannot exist any** bound state of mass μ .
- In the **degenerate** case when the interval extends to the whole real line ($\mathcal{K} = \mathcal{G}$) \Rightarrow there are **infinitely many** ground states of mass μ (the **solitons**), but **no** bound state **at higher levels**.

Nonlinearity on a “compact portion of positive measure” generates bound states at higher energies!

Sketch of the proof: Minimax methods

For every $A \subset H^1(\mathcal{G}) \setminus \{0\}$ closed and **symmetric** we define the *Krasnosel'skii genus* of A as

$$\gamma(A) = \min\{n \in \mathbb{N} : \exists f : A \rightarrow \mathbb{R}^n \setminus \{0\} \text{ continuous and odd}\}.$$

Then, introducing the **minimax classes**

$$\Gamma_j = \{A \subset M : A \text{ compact, symmetric and } \gamma(A) \geq j\},$$

we can define the **levels**

$$c_j = \inf_{A \in \Gamma_j} \max_{u \in A} E_M(u).$$

If $c_j \in \mathbb{R}$ and E_M satisfies the *Palais–Smale condition* at level c_j , then c_j is a **critical level** for E_M .

Sketch of the proof: Minimax methods

For every $A \subset H^1(\mathcal{G}) \setminus \{0\}$ closed and **symmetric** we define the *Krasnosel'skii genus* of A as

$$\gamma(A) = \min\{n \in \mathbb{N} : \exists f : A \rightarrow \mathbb{R}^n \setminus \{0\} \text{ continuous and odd}\}.$$

Then, introducing the **minimax classes**

$$\Gamma_j = \{A \subset M : A \text{ compact, symmetric and } \gamma(A) \geq j\},$$

we can define the **levels**

$$c_j = \inf_{A \in \Gamma_j} \max_{u \in A} E_M(u).$$

If $c_j \in \mathbb{R}$ and E_M satisfies the *Palais–Smale condition* at level c_j , then c_j is a **critical level** for E_M

Sketch of the proof: Minimax methods

For every $A \subset H^1(\mathcal{G}) \setminus \{0\}$ closed and **symmetric** we define the *Krasnosel'skii genus* of A as

$$\gamma(A) = \min\{n \in \mathbb{N} : \exists f : A \rightarrow \mathbb{R}^n \setminus \{0\} \text{ continuous and odd}\}.$$

Then, introducing the **minimax classes**

$$\Gamma_j = \{A \subset M : A \text{ compact, symmetric and } \gamma(A) \geq j\},$$

we can define the **levels**

$$c_j = \inf_{A \in \Gamma_j} \max_{u \in A} E_M(u).$$

If $c_j \in \mathbb{R}$ and E_M satisfies the *Palais–Smale condition* at level c_j , then c_j is a **critical level** for E_M

Sketch of the proof: Minimax methods

For every $A \subset H^1(\mathcal{G}) \setminus \{0\}$ closed and **symmetric** we define the *Krasnosel'skii genus* of A as

$$\gamma(A) = \min\{n \in \mathbb{N} : \exists f : A \rightarrow \mathbb{R}^n \setminus \{0\} \text{ continuous and odd}\}.$$

Then, introducing the **minimax classes**

$$\Gamma_j = \{A \subset M : A \text{ compact, symmetric and } \gamma(A) \geq j\},$$

we can define the **levels**

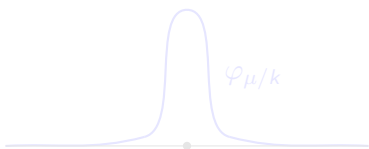
$$c_j = \inf_{A \in \Gamma_j} \max_{u \in A} E_M(u).$$

If $c_j \in \mathbb{R}$ and E_M satisfies the *Palais–Smale condition* at level c_j , then c_j is a **critical level** for E_M

Sketch of the proof: classes at negative levels

Since one can show that E_M satisfies the Palais–Smale condition **if and only if** $c < 0$, it is necessary to prove that $c_1, \dots, c_k < 0$ (**provided** μ is large!).

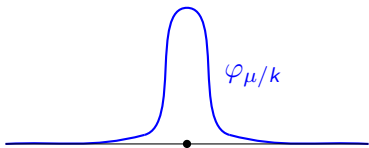
To this aim, we take a **soliton** of mass μ/k ,



Sketch of the proof: classes at negative levels

Since one can show that E_M satisfies the Palais–Smale condition **if and only if** $c < 0$, it is necessary to prove that $c_1, \dots, c_k < 0$ (**provided** μ is large!).

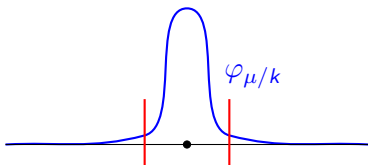
To this aim, we take a **soliton** of mass μ/k ,



Sketch of the proof: classes at negative levels

Since one can show that E_M satisfies the Palais–Smale condition **if and only if** $c < 0$, it is necessary to prove that $c_1, \dots, c_k < 0$ (**provided** μ **is large!**).

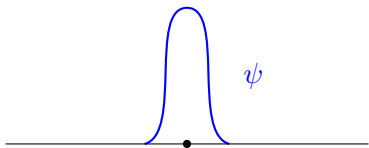
To this aim, we take a **soliton** of mass μ/k , **cut-off** its “tails”,



Sketch of the proof: classes at negative levels

Since one can show that E_M satisfies the Palais–Smale condition **if and only if** $c < 0$, it is necessary to prove that $c_1, \dots, c_k < 0$ (**provided** μ is large!).

To this aim, we take a **soliton** of mass μ/k , **cut-off** its “tails”, **lower** and **multiply** by a factor to **arrange the mass**.

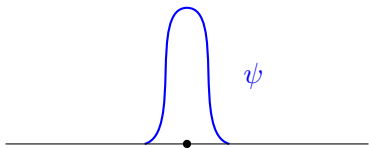


ψ is “close” to the soliton and, as $\mathcal{E}(\varphi_{\mu/j}) < 0$, has **negative energy**.

Sketch of the proof: classes at negative levels

Since one can show that E_M satisfies the Palais–Smale condition **if and only if** $c < 0$, it is necessary to prove that $c_1, \dots, c_k < 0$ (**provided** μ is large!).

To this aim, we take a **soliton** of mass μ/k , **cut-off** its “tails”, **lower** and **multiply** by a factor to **arrange the mass**.



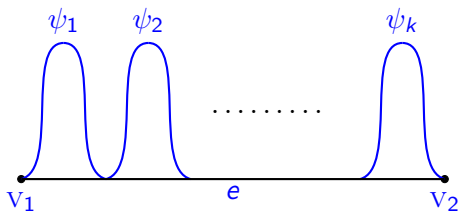
ψ is “close” to the soliton and, as $\mathcal{E}(\varphi_{\mu/j}) < 0$, has **negative energy**.

Sketch of the proof: classes at negative levels

Now, defining the function $h : S^{k-1} \rightarrow M$ as

$$h(\theta) = \sqrt{k} \sum_{i=1}^k \theta_i \psi_i,$$

with



and setting

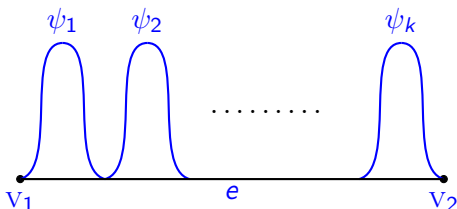
$$A = h(S^{k-1}),$$

Sketch of the proof: classes at negative levels

Now, defining the function $h : S^{k-1} \rightarrow M$ as

$$h(\theta) = \sqrt{k} \sum_{i=1}^k \theta_i \psi_i,$$

with



and setting

$$A = h(S^{k-1}),$$

Sketch of the proof: classes at negative levels

we have a **compact** and **symmetric** set with $\gamma(A) \geq k$ and $E_M(u) < 0$ for all $u \in A$.

Then, since $c_k = \inf_{A \subset \Gamma_k} \max_{u \in A} E_M(u)$, there results $c_k < 0$.
Recalling that by definition $c_1 \leq c_2 \leq \dots \leq c_k$, the proof is complete (**we had to prove** $c_1, \dots, c_k < 0!$).

Last question: where we used the fact that μ is **large**? why we need to **enlarge** μ when k increases?



Beacause we must place more and more **disjoint** copies of ψ (with **smaller and smaller** support) on e keeping **at the same time** the energy level **negative**.

Sketch of the proof: classes at negative levels

we have a **compact** and **symmetric** set with $\gamma(A) \geq k$ and $E_M(u) < 0$ for all $u \in A$.

Then, since $c_k = \inf_{A \subset \Gamma_k} \max_{u \in A} E_M(u)$, there results $c_k < 0$.
Recalling that by definition $c_1 \leq c_2 \leq \dots \leq c_k$, the proof is complete (**we had to prove** $c_1, \dots, c_k < 0!$).

Last question: where we used the fact that μ is **large**? why we need to **enlarge** μ when k increases?



Beacause we must place more and more **disjoint** copies of ψ (with **smaller and smaller** support) on e keeping **at the same time** the energy level **negative**.

Sketch of the proof: classes at negative levels

we have a **compact** and **symmetric** set with $\gamma(A) \geq k$ and $E_M(u) < 0$ for all $u \in A$.

Then, since $c_k = \inf_{A \subset \Gamma_k} \max_{u \in A} E_M(u)$, there results $c_k < 0$. Recalling that by definition $c_1 \leq c_2 \leq \dots \leq c_k$, the proof is complete (**we had to prove** $c_1, \dots, c_k < 0!$).

Last question: where we used the fact that μ is **large**? why we need to **enlarge** μ when k increases?



Beacause we must place more and more **disjoint** copies of ψ (with **smaller and smaller** support) on e keeping **at the same time** the energy level **negative**.

Sketch of the proof: classes at negative levels

we have a **compact** and **symmetric** set with $\gamma(A) \geq k$ and $E_M(u) < 0$ for all $u \in A$.

Then, since $c_k = \inf_{A \subset \Gamma_k} \max_{u \in A} E_M(u)$, there results $c_k < 0$. Recalling that by definition $c_1 \leq c_2 \leq \dots \leq c_k$, the proof is complete (**we had to prove** $c_1, \dots, c_k < 0!$).

Last question: where we used the fact that μ is **large**? why we need to **enlarge** μ when k increases?



Beacause we must place more and more **disjoint** copies of ψ (with **smaller and smaller** support) on e keeping **at the same time** the energy level **negative**.

And finally...

THANK YOU FOR YOUR ATTENTION!

Sketch of the proof: a general result

To prove the first part, one can easily find a sequence $(v_k) \subset M$ s.t. $\lim_k E_M(v_k) = 0$.

On the other hand, using the L^p -version of the **Gagliardo-Nirenberg Inequality**

$$\|u\|_{L^p(\mathcal{G})}^p \leq C_p \|u\|_{L^2(\mathcal{G})}^{\frac{p}{2}+1} \|u'\|_{L^2(\mathcal{G})}^{\frac{p}{2}-1} \quad \forall u \in H^1(\mathcal{G}),$$

there results that each **minimizing sequence** $(u_k) \subset M$ is bounded in $H^1(\mathcal{G})$.

Then $u_k \rightharpoonup u$ in $H^1(\mathcal{G})$ and, by **Rellich** Theorem, we see that

$$E(u) \leq \liminf_k E_M(u_k).$$

Since $\inf_{v \in M} E_M(v) < 0$ **prevents** $\|u\|_{L^2(\mathcal{G})}^2 < \mu$, one concludes.

Sketch of the proof: nonexistence result (1/2)

Since $\inf_{v \in M} E_M(v) \leq 0$ for all $\mu > 0$, it is **sufficient** to find $\mu_2 > 0$ s.t. for all $\mu < \mu_2$ and all $u \in M = \{u \in H^1(\mathcal{G}) : \|u\|_{L^2(\mathcal{G})}^2 = \mu\}$ there results

$$E_M(u) > 0.$$

By an **inductive argument** one sees that $E_M(u) \leq 0$ entails

$$\|u'\|_{L^2(\mathcal{G})}^2 \leq \frac{1}{C_\infty^4 \mu} \|u\|_{L^\infty(\mathcal{G})}^{4(\frac{p}{4})^{n+1}} (C_\infty^4 \mu L)^{\sum_{i=1}^n (\frac{p}{4})^i} \quad \forall n \geq 0,$$

by a repeated use of the **L^∞ -version** of GNI

$$\|u\|_{L^\infty(\mathcal{G})} \leq C_\infty \|u\|_{L^2(\mathcal{G})}^{1/2} \|u'\|_{L^2(\mathcal{G})}^{1/2} \quad \forall u \in H^1(\mathcal{G}).$$

Sketch of the proof: nonexistence result (2/2)

Then $\forall n \geq 0$

$$\|u'\|_{L^2(\mathcal{G})}^2 \leq C_p^2 \mu^3 (C_\infty^4 \mu L)^{n+1} \quad \text{if } p = 4$$

$$\|u'\|_{L^2(\mathcal{G})}^2 \leq C_p^{\frac{4}{6-p}} \mu^{\frac{p+2}{6-p}} \left(C_\infty^{\frac{4p}{p-4}} C_p^{\frac{4}{6-p}} \mu^{\frac{4(p-2)}{(p-4)(6-p)}} L^{\frac{4}{p-4}} \right)^{\left(\frac{p}{4}\right)^{n+1}-1} \quad \text{if } p > 4.$$

If the terms in brackets are < 1 , that is

$$\mu < \mu_2 = \left(L^{-1} C_p^{\frac{4-p}{6-p}} C_\infty^{-p} \right)^{\frac{6-p}{p-2}},$$

then $\|u'\|_{L^2(\mathcal{G})}^2 = 0$. Since $u \in H^1(\mathcal{G})$, there follows that $u \equiv 0$, but this is a **contradiction** with $\|u\|_{L^2(\mathcal{G})}^2 = \mu > 0 \Rightarrow E_M(u) \leq 0$.

A remark on homothety

Let $u \in M$ and $\sigma > 0$. The function $w(x) = \sigma^{\frac{2}{6-p}} u\left(\sigma^{\frac{p-2}{6-p}} x\right)$ belongs to $M_\sigma = \{v \in H^1(\mathcal{G}_\sigma) : \|v\|_{L^2(\mathcal{G}_\sigma)}^2 = \sigma\mu\}$, where \mathcal{G}_σ is a metric graph obtained from \mathcal{G} by an **homothety** of factor $\sigma^{-\frac{p-2}{6-p}}$. Moreover, $E_{M_\sigma}(w) = \sigma^{\frac{p+2}{6-p}} E_M(u)$ and hence

w is a ground state of mass $\sigma\mu$ in \mathcal{G}_σ



u is a ground state of mass μ in \mathcal{G}

Note that:

- μ_1 and μ_2 scale **coherently** with this transformation;
- one can formulate **all** the previous results in terms of L in place of μ .

Sketch of the proof: Palais-Smale condition

We say that $(u_k) \subset M$ is a *Palais-Smale sequence* at level c if

$$E_M(u_k) \rightarrow c \quad \|E'_M(u_k)\| \rightarrow 0$$

and that E_M satisfies the *Palais-Smale condition* at level c (i.e., $(PS)_c$) if each PS sequence admits a *converging subsequence* in M .

It is possible to check that E_M satisfies $(PS)_c$ only when $c < 0$:

- counterexamples for $c \geq 0$;
- standard techniques for $c < 0$.